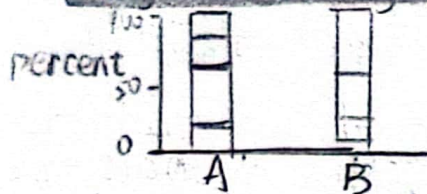
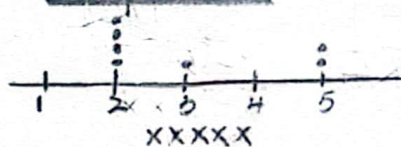


AP 统计

1. segment bar graph



dot plots



2. describe overall pattern: shape/center/spread

describe striking departure: outlier

3. unimodal: single peak

bimodal: double peaks

multimodal: more than 2 peaks

6. density curve doesn't reflect outliers, and it is an approximation

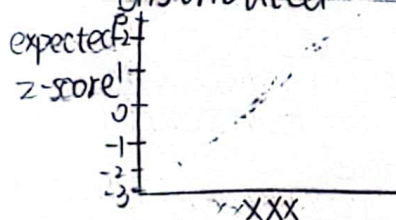
7. for normal distribution

≈ 68% of data fall within σ

≈ 95% of data fall within 2σ

≈ 99.7% of data fall within 3σ

• if the points on a normal probability plot close to a straight line, the data are approximately normally distributed.



if a is β percentile
 $\phi(\beta) = a$
 we plot (a, β)

outliers appear as points that are far away from overall pattern of the plot

11. regression line: 回归曲线: $\hat{y} = ax + b$

描述当自变量变化时因变量的变化程度

• extrapolation: 外推法

用 interval 之外的自变量推因变量, 不一定 accurate

• residual: 推导值与真实值之差 $y - \hat{y}$

• least square regression line:
 make the sum of squared residuals as small as possible

• residual plot:

a scatterplot of residuals against explanatory variable

when obvious pattern occurred in residual plot, model isn't appropriate

4. pth percentile: $p\%$ 数据比其小

5. standardized score (z-score)

$$z = \frac{x - \bar{x}}{\sigma}$$

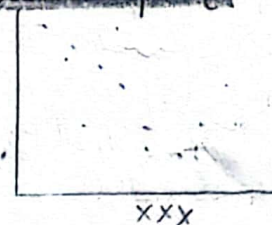
one data is z standard deviation below/above the mean

用这个比来交两次的数据位置

8. explanatory variable: "自变量"
response variable: "因变量"

9. scatter plot

x
y



explanatory variable:
 horizontal axis,
 response variable:
 vertical axis,
 every data as a point

描述: direction, form, strength

从哪个方向 直线曲线 相关性
 到哪个方向 clusters

outliers

10. 相关系数: $r = \frac{1}{n-1} \sum z_x z_y$

• doesn't imply causation

• ignores the distinction between explanatory & response variables

• isn't affected by changes in unit of measurement

• isn't resistant

• standard deviation of residuals

$$s = \sqrt{\frac{\sum (y_i - \hat{y}_i)^2}{n-2}}$$

• coefficient of determination

$$r^2 = 1 - \frac{\sum \text{residuals}^2}{\sum (y_i - \bar{y})^2}$$

如果用 y 估计, 我们就能得到一个 corresponding squared residuals. 这个数据与最小值的比反映了有多少程度的因变量是不被自变量影响的

- for X, Y , least-squared regression line is $\hat{y} = \alpha x + b$ where $\alpha = r \frac{s_y}{s_x}$, $b = \bar{y} - \alpha \bar{x}$

13. experiment (VS observational study)

- when goal is to understand cause and effect, experiments are only source of fully convincing data
- confounding: two variables are associated in such a way that their effects on a response variable cannot be distinguished from each other
- treatment: specific condition applied to individuals in an experiment
- experimental unit: smallest collection of individuals to which treatments are applied
- subject: when units are human beings
- factor: explanatory variables
- level: treatment formed by combining a specific value
- principles of experimental design: comparison + random assignment + control + replication
- completely randomized design: the experimental units are assigned to the treatment completely by chance (not necessarily equal numbers)
- control group: 对照组
- double-blind experiment: neither the subjects nor those who interact with them and measure the response variable know which treatment a subject received
- statistically significant: an observed effect so large that it would rarely occur by chance

12. data collection

convenience survey: 便利抽样
快速得出结论但 bias

• stratified random sample: 分层抽样
strata: 层

starting by classify the population in to groups of similar individuals (strata), then choose a separate SRS in each stratum and combine these SRSs to form the sample

it works best when the individuals within each stratum are similar with respect to what is being measured and when there are large differences between strata

• cluster sample: 聚类样本

start by classifying the population into groups of individuals, that are located near to each other, (cluster), then choose an SRS of the cluster

• difference between stratified random & cluster sample

前者分成多个小题目, 后者分为多个小 population

• undercoverage: occurs when some members of the population cannot be chosen in a sample

• nonresponse: occurs when an individual chosen for the sample can't be contacted or refuses to participate
nonresponse $\neq$ voluntary response

前者已选好 sample, 后者在选 sample

• response bias

a systematic pattern of inaccurate answers in a survey
wording of questions

observational

• block: a group of experimental units that are known before the experiment to be similar in some way that is expected to affect the response to the treatment
randomized block design
the random assignment

experimental units to treatment
TS carried out separately within
each block

matched pairs design: a common
form of blocking for comparing
just two treatments

15. sample space S: set of all
possible outcomes of a
process

probability model sample
space S + probabilities

16. • parameter describes population.
statistic describes sample
in population $\mu \in P, N$
in sample $\bar{x} \in S, n$

• sample distribution: the distribution
of values taken by statistic in
all possible samples of the same
size from the same population

• variability of a statistic: spread
of its sampling distribution,
determined by sizes of samples

• sample distribution of $\hat{p}$

$$\mu_{\hat{p}} = P \quad \sigma_{\hat{p}} = \sqrt{\frac{P(1-P)}{n}} \text{ for } n \leq \frac{1}{10}N$$

if $np > 10, nq > 10$, approximately normal
sample distribution of $\bar{x}$

$$\mu_{\bar{x}} = \mu \quad \sigma_{\bar{x}} = \frac{\sigma}{\sqrt{n}} \text{ for } n \leq \frac{1}{10}N$$

if $n \geq 30$, central limit theorem (CLT)
distribution will be approximately
normal

• CI for μ $\bar{x} \pm t_{\text{critical}} \frac{s}{\sqrt{n}}$

$$t = \frac{\bar{x} - \mu}{\frac{s}{\sqrt{n}}}$$

注意, t 的自由度是 $n-1$, 如果是自
要求自由度没有, 用 the greatest df
available that is less than your
desired
conditions

① well-design random sample or

14. make conclusion

individuals randomly
assigned to groups

were individuals
randomly selected

	S	N
1	P, C&E	P
n	C&E	

P: inference about population

C&E: inference about cause and effect

• 有时 experiment 不能完成因为不现实,
因此我们只能通过 observational
study to make conclusions

因此, 要想 conclude, 满足

① association is strong

② association is consistent

③ larger values of explanatory variable
are associated with stronger
response

④ the alleged cause precedes the effect
in time

⑤ the alleged cause is plausible

17. point estimator

a statistic that provides an
estimate of a population
parameter. the value is
point estimate

• confidence interval

we are C% confident that the
interval from — to — captures
the —

• CI for P $\hat{p} \pm Z_{\text{critical}} \sqrt{\frac{\hat{p}(1-\hat{p})}{n}}$
conditions

① data comes from a well-design
random sample or randomized
experiment

② if without replacement, $n \leq \frac{1}{10}N$

③ both $n\hat{p}, n\hat{q} > 10$

sometimes 我们要确定 n 大于

$$Z_{\text{critical}} \sqrt{\frac{\hat{p}(1-\hat{p})}{n}} < ME_{\text{max}} < ME_{\text{want}}$$

where ME_{max} , maximum margin
of error occurs when $p = 0.5$

• standard error

when the standard deviation of
a statistic is measured from the
data.

randomized experiment

- ① if without replacement, $n \leq \frac{1}{10}N$
- ② population has a normal distribution or $n \geq 30$, if distribution unknown and $n < 30$, use a graph of sample data to assess the normality of population, don't use t procedure if graph shows skewness or outliers - sometimes, need to find n first
- $Z_{critical} \cdot \frac{\sigma}{\sqrt{n}} \leq ME_{want}$
其中 σ 是先前实验的结果

19. difference between p_1 and p_2

- ① for $|p_1 - p_2|$:

$$\mu \hat{p}_1 - \hat{p}_2 = p_1 - p_2$$

$$\sigma \hat{p}_1 - \hat{p}_2 = \sqrt{\sigma_{\hat{p}_1}^2 + \sigma_{\hat{p}_2}^2} = \sqrt{\frac{p_1(1-p_1)}{n_1} + \frac{p_2(1-p_2)}{n_2}}$$

$\hat{p}_1 - \hat{p}_2$ is approximately normal if

$$n_1 p_1, n_1(1-p_1), n_2 p_2, n_2(1-p_2) \geq 10$$

$$\text{CI} = (\hat{p}_1 - \hat{p}_2) \pm Z_{critical} \sqrt{\frac{\hat{p}_1(1-\hat{p}_1)}{n_1} + \frac{\hat{p}_2(1-\hat{p}_2)}{n_2}}$$

$$Z_{critical} = \frac{(\hat{p}_1 - \hat{p}_2) - 0}{\sqrt{\frac{\hat{p}_c(1-\hat{p}_c)}{n_1} + \frac{\hat{p}_c(1-\hat{p}_c)}{n_2}}}$$

$$\text{where } \hat{p}_c = \frac{\hat{x}_1 + \hat{x}_2}{n_1 + n_2}$$

(pooled sample proportion)

• difference for μ

- ① for $\mu_1 - \mu_2$:

$$\mu \bar{x}_1 - \bar{x}_2 = \mu_1 - \mu_2$$

$$\sigma \bar{x}_1 - \bar{x}_2 = \sqrt{\frac{\sigma_1^2}{n_1} + \frac{\sigma_2^2}{n_2}}$$

$\bar{x}_1 - \bar{x}_2$ is approximately normal if

$$n_1, n_2 \geq 30$$

$$t_{critical} = \frac{(\bar{x}_1 - \bar{x}_2) - (\mu_1 - \mu_2)}{\sqrt{\frac{S_1^2}{n_1} + \frac{S_2^2}{n_2}}}$$

use t distribution with degrees of freedom equal to $\min(n_1 - 1, n_2 - 1)$

$$CI: (\bar{x}_1 - \bar{x}_2) \pm t_{critical} \sqrt{\frac{S_1^2}{n_1} + \frac{S_2^2}{n_2}}$$

[paired 只在同一组人经历两种 treatments 时使用]

18. 假设检验

- P-value: 如果 H_0 成立, 那么发生该事件或更极端事件概率
- statistically significant at level α : P-value $\leq \alpha$
- 在 α significant level 的假设检验中 $\alpha = P(\text{Type I error} | H_0 \text{ is true})$
- power of a test against a specific alternative is the probability that the test will reject H_0 at a chosen significant level α when the specified alternative value of the parameter is true
- $P(\text{Type I})$ 与 $P(\text{Type II})$, 一个下降则另一个上升
- increase power by:
 - ① increase sample size
 - ② increase α
 - ③ increase the difference that is important to detect between null and alternative parameter values
- 对 p 检验用 z , 对 μ 检验用 t (自由度 $n-1$, 找不到就向下取整)
- 影响 α size 增加因素
 - ① smaller significant level: need stronger evidence to reject H_0
 - ② higher power: higher power gives a better chance of detecting a difference when it exists
 - ③ smaller effect size
- 注: significant $\neq$ important

20. chi-square distribution

自由度为 $n-1$

$$\text{mean} = n$$

$$\text{mode} = n - 2$$

condition:

- ① well-designed random sample or randomized experiment

$$\text{② } n \leq \frac{1}{10}N$$

- ③ all expected counts ≥ 5
- reject H_0 , 最大的 component $(\frac{O_i - E_i}{E_i})^2$



2) regression

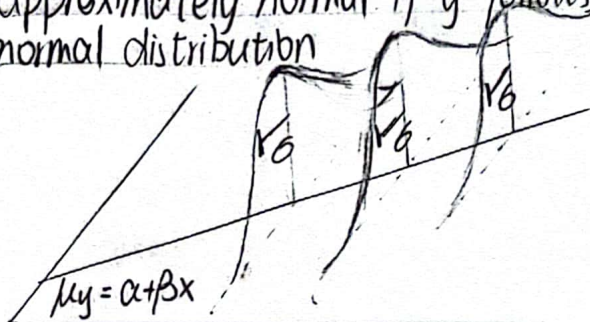
- choose an SRS of n observations (a, b) from a population of size N with least-squares regression line (population)

predict $y = \alpha + \beta x$

let b be the slope of the sample regression line. then

$$\mu_b = \beta \quad \sigma_b = \frac{\sigma_y}{\sigma_x \sqrt{n}} \text{ as long as } n \leq \frac{1}{10}N$$

where σ_x is the SD of N observations. the sample distribution of b is approximately normal if y follows a normal distribution



2) transforming to achieve linearity

- power model $y = ax^p \Rightarrow (x^p, y) / (x, y)$
- exponential model $y = ab^x \Rightarrow (x, \ln y)$

condition:

① linear: use scatter plot, centred at residual = 0

② independent

if without replacement, $n \leq \frac{1}{10}N$

③ normal stemplot/histogram/normal probability plot

④ equal SD: no matter value of x .

⑤ look at the scatter of the residuals above and below the 'residual = 0' line: vertical spread should be same no matter the value of x

⑥ random

• CI of $\beta = b \pm t_{\text{critical}} \frac{s}{\sigma_x \sqrt{n-1}}$

where $s = \sqrt{\frac{\sum (y_i - \hat{y}_i)^2}{n-2}}$

$$\sigma_x = \sqrt{\frac{\sum (x - \bar{x})^2}{n-1}}$$

t 的自由度为 $n-2$

• $t = \frac{b - \beta}{\frac{s}{\sigma_x \sqrt{n-1}}}$

t 的自由度为 $n-2$.

判断有无 linear 关系, $H_0: \beta = 0$

AP 微积分

1. δ 与 ϵ 语言

2. 夹逼. 通分有理化 (if $g(x) = f(x)$ for $x \neq c$, then $\lim_{x \rightarrow c} f(x) = \lim_{x \rightarrow c} g(x)$)

3. (derivative) differentiability $\rightarrow$ continuity, 不能反推

4. rolle's theorem: let $f(x)$ be continuous on the closed interval $[a, b]$, and differentiable on the open interval (a, b) . if $f(a) = f(b)$, then there is at least one number c in (a, b) such that $f'(c) = 0$

mean value theorem: if $f(x)$ is continuous on the closed interval $[a, b]$ and differentiable on the open interval (a, b) , then there exists a number c in (a, b) such that $f'(c) = \frac{f(b) - f(a)}{b - a}$

Proof: line passing through $(a, f(a)), (b, f(b))$

$$y = \left(\frac{f(b) - f(a)}{b - a} \right) (x - a) + f(a) \quad [\text{注意 } \frac{f(b) - f(a)}{b - a} \text{ 与 } f(a) \text{ 为 constant}]$$

let $g(x)$ be the difference between $f(x)$ and y

$g(a) = g(b) = 0$, since $f(x)$ is continuous, so does $g(x)$

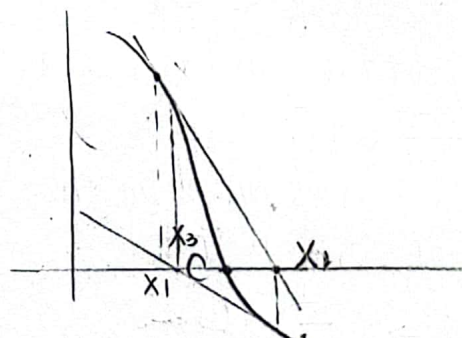
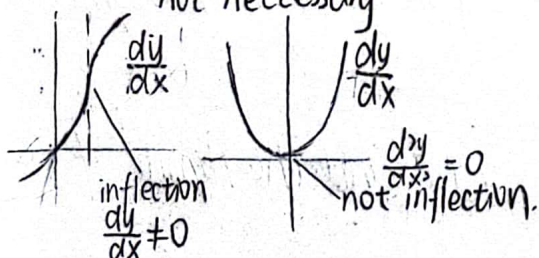
exist c on (a, b) satisfying $g'(c) = 0$

$$g(x) = f(x) - y = f(x) - \left(\frac{f(b) - f(a)}{b - a} \right) (x - a) - f(a)$$

$$g'(x) = f'(x) - \frac{f(b) - f(a)}{b - a} \quad g'(c) = 0 \quad f'(c) = \frac{f(b) - f(a)}{b - a}$$

5. inflection: the point when concave upwards (downwards) turns into downwards (upwards)

$\frac{d^2y}{dx^2} = 0$ $\xrightarrow[\text{not necessary}]{\text{not necessary}}$ inflection $\xrightarrow[\text{must be}]{\text{not necessary}}$ turning point (max/min)



6. Newton's method of approximation

let $f(c) = 0$, where $f(x)$ is differentiable on an open interval containing c . we want to find an approximation of c [the boundary of the interval]

• make an initial estimate x_1

• $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$, again and again.

because: tangent passing through x_1 $y - f(x_1) = f'(x_1)(x - x_1)$
 $y = f'(x_1)(x - x_1) + f(x_1)$

$$\text{when } y = 0 \quad x = x_1 - \frac{f(x_1)}{f'(x_1)}$$

into to successfully use this method $\left| \frac{f(x)f''(x)}{[f'(x)]^2} \right| < 1$.

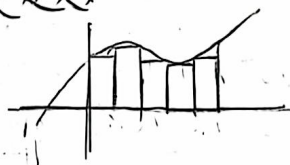
7. when $\Delta x \rightarrow 0$, $\Delta y \rightarrow dy$:

$$\Delta y = f(x + \Delta x) - f(x), \quad dy = f'(x)dx$$

• find the area (integral) of graph in $[a, b]$ (不是定义)

$$\Delta x (\text{步长}) = \frac{b-a}{n}, \quad A = \sum_{i=1}^n f(a + n\Delta x) \cdot \Delta x$$

$$\int_a^b f(x) dx = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(a + n\Delta x) \Delta x$$



[可以设每一项取 upper/lower limit 来界定 boundaries. 当 $n \rightarrow \infty$ 时每一项的 upper limit = lower limit]

let f be continuous and nonnegative on the interval $[a, b]$; the limits as $n \rightarrow \infty$ of both the lower and upper sums exist and are equal to each other.

$$\lim_{n \rightarrow \infty} S(n) = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(m_i) \Delta x = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(M_i) \Delta x = \lim_{n \rightarrow \infty} S(n)$$

where $\Delta x = \frac{b-a}{n}$ and $f(m_i)$ and $f(M_i)$ are the minimum and maximum value of f on the subinterval J .

• let f be defined on the closed interval $[a, b]$ and let Δ be a partition of $[a, b]$ given by

$$a = x_0 < x_1 < x_2 < \dots < x_{n-1} < x_n = b$$

where Δx_i is the width of the i th subinterval. if C_i is any point in the i th subinterval $[x_{i-1}, x_i]$, then the sum (中值定理)

$$\sum_{i=1}^n f(C_i) \Delta x_i, \quad x_{i-1} \leq C_i \leq x_i$$

is called the Riemann sum of f for the partition Δ

the width of the largest subinterval of a partition Δ is the norm of the partition and is denoted by $\|\Delta\|$

$$\frac{b-a}{\|\Delta\|} \leq n$$

• if f is defined on the closed interval $[a, b]$ and the limit of Riemann sums over partition Δ

$$\lim_{\|\Delta\| \rightarrow 0} \sum_{i=1}^n f(C_i) \Delta x_i$$

exists, then f is said to be integrable on $[a, b]$ and the limit is denoted by

$$\lim_{\|\Delta\| \rightarrow 0} \sum_{i=1}^n f(C_i) \Delta x_i = \int_a^b f(x) dx$$

(可用 ϵ 与 δ 语言表示)

• if a function f is continuous on the closed interval $[a, b]$ and F is an antiderivative of f on the interval $[a, b]$, then

$$\int_a^b f(x) dx = F(b) - F(a)$$

proof. let Δ be any partition of $[a, b]$

$$a = x_0 < x_1 < x_2 < \dots < x_{n-1} < x_n = b$$

$$F(b) - F(a) = F(x_n) - F(x_{n-1}) + F(x_{n-1}) - F(x_{n-2}) + \dots + F(x_1) - F(x_0)$$

$$= \sum_{i=1}^n [F(x_i) - F(x_{i-1})]$$

by mean value theorem, there exists a number c_i in the i th subinterval.

$$F'(c_i) = \frac{F(x_i) - F(x_{i-1})}{x_i - x_{i-1}} = f(c_i)$$

$$\because x_i - x_{i-1} = \Delta x \text{ and } F'(c_i) = f(c_i):$$

$$F(b) - F(a) = \sum_{i=1}^n f(c_i) \Delta x_i$$

$$\bullet \frac{d}{dx} \left[\int_a^x f(t) dt \right] = f(x)$$

proof. defining $F(x) = \int_a^x f(t) dt$

$$F'(x) = \lim_{\Delta x \rightarrow 0} \frac{F(x + \Delta x) - F(x)}{\Delta x}$$

$$= \lim_{\Delta x \rightarrow 0} \frac{1}{\Delta x} \left[\int_a^{x+\Delta x} f(t) dt - \int_a^x f(t) dt \right]$$

$$= \lim_{\Delta x \rightarrow 0} \frac{1}{\Delta x} \int_x^{x+\Delta x} f(t) dt$$

by mean value theorem, we can find a value of $c: \int_x^{x+\Delta x} f(t) dt = f(c) \Delta x$

$$F'(x) = \lim_{\Delta x \rightarrow 0} \frac{1}{\Delta x} f(c) \Delta x = \lim_{\Delta x \rightarrow 0} f(c)$$

$$\because x \leq c \leq x + \Delta x$$

$$\therefore F'(x) = \frac{d}{dx} \left[\int_a^x f(t) dt \right] = f(x)$$

8. find the approximation of an integral: Simpson's Rule

if $p(x) = Ax^2 + Bx + C$:

$$\int_a^b p(x) dx = \int_a^b Ax^2 + Bx + C dx = \left[\frac{Ax^3}{3} + \frac{Bx^2}{2} + Cx \right]_a^b$$

$$= \frac{A}{3}(b^3 - a^3) + \frac{B}{2}(b^2 - a^2) + C(b - a)$$

$$= \frac{b-a}{6} [2A(a^2 + ab + b^2) + 3B(b+a) + 6C]$$

$$= \frac{b-a}{6} [p(a) + 4p(\frac{a+b}{2}) + p(b)]$$

We partition interval $[a, b]$ into n subinterval, each of width $\Delta x = \frac{b-a}{n}$. where n is an even, and the subintervals are grouped in pairs such that

$$a = x_0 < x_1 < x_2 < x_3 < x_4 < \dots < x_{n-2} < x_{n-1} < x_n = b$$

$$[x_0, x_2] \quad [x_2, x_4] \quad \dots \quad [x_{n-2}, x_n]$$

on each double subinterval $[x_{i-2}, x_i]$, we can approximate f by a polynomial p of degree less than or equal to 2.

$$\int_{x_0}^{x_2} f(x) dx \approx \int_{x_0}^{x_2} p(x) dx = \frac{x_2 - x_0}{6} [p(x_0) + 4p(\frac{x_0 + x_2}{2}) + p(x_2)]$$

$$= \frac{b-a}{3n} [f(x_0) + 4f(x_1) + f(x_2)]$$

$$\therefore \int_a^b f(x) dx \approx \frac{b-a}{3n} [f(x_0) + 4f(x_1) + 2f(x_2) + 4f(x_3) + \dots + 4f(x_{n-1}) + f(x_n)]$$



If f has a continuous second derivative on $[a, b]$, then the error E in approximating $\int_a^b f(x) dx$ by the Trapezoidal Rule is

$$|E| \leq \frac{(b-a)^3}{12n^2} [\max |f''(x)|], \quad a \leq x \leq b$$

if f has a continuous fourth derivative on $[a, b]$, then the error E in approximating $\int_a^b f(x) dx$ by Simpson's Rule is

$$|E| \leq \frac{(b-a)^5}{180n^4} [\max |f^{(4)}(x)|], \quad a \leq x \leq b$$

9. let f be a function that is differentiable on an interval I . if f has an inverse function g , then g is differentiable at any x for which $f'(g(x)) \neq 0$. moreover

$$g'(x) = \frac{1}{f'(g(x))}, \quad f'(g(x)) \neq 0. \quad \left(\frac{dy}{dx} = \frac{1}{\frac{dx}{dy}} \right)$$

$$10. \frac{d}{dx}(a^x) = \ln a \cdot a^x \quad \frac{d}{dx}(\log_a x) = \frac{1}{x \ln a} \quad \lim_{x \rightarrow \infty} \left(1 + \frac{1}{x}\right)^x = e$$

$$\frac{d}{dx} \operatorname{arccot} x = -\frac{1}{1+x^2} \quad \frac{d}{dx} \operatorname{arcsec} x = \frac{1}{|x| \sqrt{x^2-1}} \quad \frac{d}{dx} \operatorname{arccsc} x = -\frac{1}{|x| \sqrt{x^2-1}}$$

$$\int \frac{1}{x \sqrt{x^2-a^2}} dx = \frac{1}{a} \operatorname{arcsec} \frac{|x|}{a} + C$$

$$\coth^{-1} x = \frac{1}{2} \ln \frac{x+1}{x-1} \quad \operatorname{sech}^{-1} x = \ln \frac{1+\sqrt{1-x^2}}{x} \quad \operatorname{csch}^{-1} x = \ln \left(\frac{1}{x} + \frac{\sqrt{1+x^2}}{|x|} \right)$$

$$\int \frac{1}{u \sqrt{u^2+a^2}} du = \ln(u + \sqrt{u^2+a^2}) \quad \int \frac{1}{a^2-u^2} du = \frac{1}{2a} \ln \left| \frac{a+u}{a-u} \right| \quad \int \frac{1}{u \sqrt{a^2 \pm u^2}} du = -\frac{1}{a} \ln \frac{a + \sqrt{a^2 \pm u^2}}{|u|}$$

11. euler's method of approximating the particular solution of DE

for $y' = F(x, y)$ and a small value of h

start with (x_0, y_0) , $x_1 = x_0 + h$, $y_1 = y_0 + h F(x_0, y_0)$

$x_2 = x_1 + h$, $y_2 = y_1 + h F(x_1, y_1)$

12. homogeneous differential equation of solving DE

if $f(tx, ty) = t^n f(x, y)$, then $f(x, y)$ is homogeneous of degree n .

a homogeneous differential equation is an equation is the form of

$$M(x, y) dx + N(x, y) dy = 0$$

where $M(x, y)$ and $N(x, y)$ are homogeneous functions of some degree in this way, the equation can be transformed into a differential equation whose variables are separable by substitution

$y = vx$, where v is differentiable function of x

- 在解DE时, 我们一般会写出一组解, 我们称这样的一组解 family of curve 两个 families of curves 如果 intersection 时一直都 normal, 我们称 mutually orthogonal. each curve in one of the families is called an orthogonal trajectory of the other family

A rational function is the quotient of two polynomial functions.
 注意: 这一块 $N(t)$ 的推导来源于, if $\vec{r}(t) \cdot \vec{r}(t) = C$, then $\vec{r}(t) \cdot \vec{r}'(t) = 0$,
 if a convergent alternating series exists for the ...

求每对 orthogonal trajectories

if $\frac{dy}{dx} = F(x, y)$, 我们只要找 $\frac{dy}{dx} = -\frac{1}{F(x, y)}$ 的 solution 即可

• Bernoulli Equation $\frac{dy}{dx} + P(x)y = Q(x)y^n$

we only focus on the situation when $n \neq 0$ or 1

$$y^{-n} \frac{dy}{dx} + P(x)y^{1-n} = Q(x)$$

$$(1-n)y^{-n} \frac{dy}{dx} + (1-n)P(x)y^{1-n} = (1-n)Q(x)$$

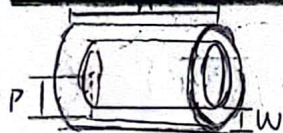
$$\frac{d}{dx}[y^{1-n}] + (1-n)P(x)y^{1-n} = (1-n)Q(x)$$

$$\text{let } z = y^{1-n}: \frac{dz}{dx} + (1-n)P(x)z = (1-n)Q(x)$$

13. 用积分求体积/做功/CoG/力

• $V = \int_a^b A dx$ [这里 A 的表达式可能与 x 有关]

• shell method 对于一个有 hole 的 cylinder



p : average radius
 h : height
 w : thickness

$$\Delta V = V_{\text{cylinder}} - V_{\text{hole}}$$

$$= \pi \left(p + \frac{w}{2} \right)^2 h - \pi \left(p - \frac{w}{2} \right)^2 h$$

$$= 2\pi w p h$$

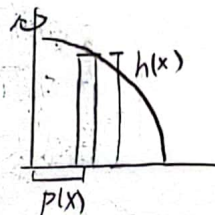
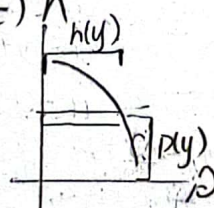
绕 x -axis 旋转

$$V = 2\pi \int_a^b p(y) h(y) dy$$

绕 y -axis 旋转

$$V = 2\pi \int_a^b p(x) h(x) dx$$

[注意, 此方法重点为找 cylinder-hole! 所以说, 注意 p 与 h 用 x 还是 y 表述]



$$W = \int F dx$$

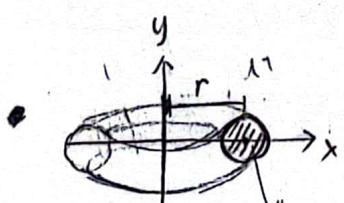
[注意, 可以是 $\Delta F \cdot x$ 与 $F \cdot \Delta x$, 要搞明白 F 与 x]

气体: $W = \int \frac{k}{v} dv$, where $p = \frac{k}{v}$, p is pressure

阴影的 CoG: $\bar{y} = \frac{\rho \int_a^b \left[\frac{f(x)+g(x)}{2} \right] [f(x)-g(x)] dx}{\int_a^b f(x)-g(x) dx}$



$$\bar{x} = \frac{\rho \int_a^b x [f(x)-g(x)] dx}{\int_a^b f(x)-g(x) dx}$$



截面绕 y 轴旋转

$$V = 2\pi r A, \text{ where } A: \text{截面面积}$$

r : 截面中心至旋转轴距离



水箱内竖放物体受水的作用力:

$$F = w \int_c^a h(y) L(y) dy, \text{ where } w \text{ is weight-density}$$

$h(y)$ is the depth of fluid.
 $L(y)$ is the horizontal length

14. 三角函数积分

- $$\int \sin^{2k+1} x \cos^n x dx = \int \sin^{2k} x \cos^n x (\sin x dx)$$

$$\int \sin^n x \cos^{2k+1} x dx = \int \sin^n x \cos^{2k} x (\cos x dx)$$

$$\left. \begin{aligned} \int \sin^{2k+1} x \cos^n x dx &= \int \sin^{2k} x \cos^n x (\sin x dx) \\ \int \sin^n x \cos^{2k+1} x dx &= \int \sin^n x \cos^{2k} x (\cos x dx) \end{aligned} \right\} \sin^2 x + \cos^2 x = 1$$
- if n is odd $\int_0^{\frac{\pi}{2}} \cos^n x dx = \frac{2}{3} \cdot \frac{4}{5} \cdot \frac{6}{7} \cdots \left(\frac{n}{n}\right)$
 if n is even ($n \geq 2$) $\int_0^{\frac{\pi}{2}} \cos^n x dx = \frac{1}{2} \cdot \frac{3}{4} \cdot \frac{5}{6} \cdots \left(\frac{n-1}{n}\right) \cdot \frac{\pi}{2}$
 similarly if turn $\cos^n x$ into $\sin^n x$
- $$\int \sec^{2k} x \tan^n x dx = \int (\sec^2 x)^{k-1} \tan^n x (\sec x dx)$$

$$\int \sec^n x \tan^{2k+1} x dx = \int \sec^{n-1} x (\tan^2 x)^k (\sec x \tan x dx)$$

$$\left. \begin{aligned} \int \sec^{2k} x \tan^n x dx &= \int (\sec^2 x)^{k-1} \tan^n x (\sec x dx) \\ \int \sec^n x \tan^{2k+1} x dx &= \int \sec^{n-1} x (\tan^2 x)^k (\sec x \tan x dx) \end{aligned} \right\} 1 + \tan^2 x = \sec^2 x$$

$$\int \tan^n x dx = \int \tan^{n-2} x (\sec^2 x - 1) dx$$

$$\int \sec^{2k+1} x dx : \text{use integration by parts}$$
- 三角函数转化:
 for $\sqrt{a^2 - u^2}$: $u = a \sin \theta$ $\int \sqrt{a^2 - u^2} du = \frac{1}{2} (a^2 \sin^{-1} \frac{u}{a} + u \sqrt{a^2 - u^2})$
 for $\sqrt{a^2 + u^2}$: $u = a \tan \theta$ $\int \sqrt{a^2 + u^2} du = \frac{1}{2} (u \sqrt{u^2 + a^2} + a^2 \ln |u + \sqrt{u^2 + a^2}|)$
 for $\sqrt{u^2 - a^2}$: $u = a \sec \theta$ $\int \sqrt{u^2 - a^2} du = \frac{1}{2} (u \sqrt{u^2 - a^2} - a^2 \ln |u + \sqrt{u^2 - a^2}|)$

15. 洛比达* 如果 variable 在指数上, turn $y = f(x)$ into $\ln y = \ln f(x)$
 对 $\ln y$ 洛比求 y

16. Integral test 求 series 是否 converge

- 保证 $f(x)$ is positive and continuous and decreasing from start
 - 用 inscribe 证明 $(\int_1^{\infty} f(x) dx)$
- direct comparison test 求 series 是否 converge/diverge
 if $0 < a_n \leq b_n$ for all n .
 if $\sum_{n=1}^{\infty} b_n$ converges, so does $\sum_{n=1}^{\infty} a_n$; if $\sum_{n=1}^{\infty} a_n$ diverges, so does $\sum_{n=1}^{\infty} b_n$
 - limit comparison test 求 series 是否 converge/diverge
 if $a_n > 0, b_n > 0$ for all n .
 $\lim_{n \rightarrow \infty} \left(\frac{a_n}{b_n} \right) = L$ where L is finite and positive
 then $\sum_{n=1}^{\infty} a_n$ and $\sum_{n=1}^{\infty} b_n$ both converge or diverge
 对于 $\sum_{n=0}^{\infty} a_n x^n$; limit 取 $\frac{x^N}{x^M}$, 如果有 c^n 的话为位置 copy
 - series with alternative signs (alternative-sign test 求 series converge)
 let $a_n > 0$, the $\sum_{n=1}^{\infty} (-1)^n a_n$ and $\sum_{n=1}^{\infty} (-1)^{n+1} a_n$ converge if
 $\lim_{n \rightarrow \infty} a_n = 0$ and $a_{n+1} \leq a_n$ for all n

if a convergent alternating series satisfies the condition $a_{n+1} \leq a_n$ then the absolute value of the remainder R_n involved in approximating the sum S by S_n is less than (or equal to) the first neglect term.

$$|S - S_n| = |R_n| \leq a_{n+1}$$

- if $\sum |a_n|$ converges, so does $\sum a_n$

$\sum a_n$ is absolutely convergent if $\sum |a_n|$ converges

$\sum a_n$ is conditionally convergent if $\sum a_n$ converges but $\sum |a_n|$ diverges

- n-th term test $\nmid$ series diverge if $\lim_{n \rightarrow \infty} a_n \neq 0$, $\sum_{n=1}^{\infty} a_n$ diverge

- p-series $\nmid$ series diverge or converge

for $\sum_{n=1}^{\infty} \frac{1}{n^p}$: when $p > 1$, converge, when $0 \leq p \leq 1$, diverge

- ratio test $\nmid$ series diverge or converge

$\sum a_n$ converges absolutely if $\lim_{n \rightarrow \infty} \left| \frac{a_{n+1}}{a_n} \right| < 1$

$\sum a_n$ diverges if $\lim_{n \rightarrow \infty} \left| \frac{a_{n+1}}{a_n} \right| > 1$ or $\lim_{n \rightarrow \infty} \left| \frac{a_{n+1}}{a_n} \right| = \infty$

ratio test is inconclusive if $\lim_{n \rightarrow \infty} \left| \frac{a_{n+1}}{a_n} \right| = 1$

- root test $\nmid$ series diverge or converge

$\sum a_n$ converges absolutely if $\lim_{n \rightarrow \infty} \sqrt[n]{|a_n|} < 1$

$\sum a_n$ diverges if $\lim_{n \rightarrow \infty} \sqrt[n]{|a_n|} > 1$ or $\lim_{n \rightarrow \infty} \sqrt[n]{|a_n|} = \infty$

root test is inconclusive if $\lim_{n \rightarrow \infty} \sqrt[n]{|a_n|} = 1$

- strategy judging series divergent or convergent

1. nth approach 0?

2. special types? $\rightarrow$ geometric, p-series, telescoping, alternating

3. can integral test, root test, ratio test applied?

4. can it be compared to one of special types?

- 17. taylor polynomial $f(x) = f(c) + f'(c)(x-c) + \frac{f''(c)}{2!}(x-c)^2 + \dots + \frac{f^{(n)}(c)}{n!}(x-c)^n$

• maclaurin polynomial $f(x) = f(0) + f'(0)x + \frac{f''(0)}{2!}x^2 + \dots + \frac{f^{(n)}(0)}{n!}x^n$

• for taylor polynomial $P_n(x)$, its error $R_n(x)$ is

$$|R_n(x)| = |f(x) - P_n(x)|$$

taylor theorem: if f is differentiable through order $n+1$ at interval I containing c , for each x in I , there exists z between x and c .

$$R_n(x) = \frac{f^{(n+1)}(z)}{(n+1)!} (x-c)^{n+1}$$

when $n=0$, $z=c$

18: 若 x is a variable, then an infinite series of the form $\sum_{n=0}^{\infty} a_n x^n$ is called a power series. More generally, an infinite series of the form $\sum_{n=0}^{\infty} a_n (x-c)^n$ is called a power series centered at c .
 for a power series centered at c , there exists a real number $R > 0$ such that the series converges absolutely for $|x-c| < R$, and diverge for $|x-c| > R$. R is called the radius of convergence and the set of all values of x for which series converges is interval of convergence.

- 求 R : 用 test (ratio test 居多) 求出一个结果, 然后看如果满足 test 的 converge 要求 x 要怎样.

求 interval of convergence: 两端 endpoint 的 converge 情况要独立代入验证.

- 将 power series 求导/积分后, 原有的 R 不变, 但 endpoint 的情况可能变。有时将复杂形式求积分/导数推 interval.

- geometric power series 改写

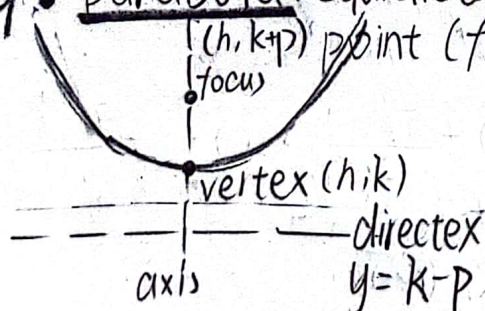
$$\sum_{n=0}^{\infty} ar^n = \frac{a}{1-r}, \quad |r| < 1 \quad \text{硬凑形式即可}$$

- operation with power series may change the interval of convergence (并集)

所以说对于一些复杂的 geometric power series 的分数形式, 先 partial, 再分别求完 interval 后看并集

- taylor 展开时, 对于一些难求导的部分 $f(x)$, 先设 $g(x) =$ 简单部分 $\times$ 再换成 $f(g(x))$ 即可
也可将其换为两个好算的展开的积/商

19. parabola: equidistance from a fixed line (directrix) and a fixed point (focus)



given that vertex is (h, k)

if directrix is $y = k-p$, focus is $(h, k+p)$

curve: $(x-h)^2 = 4p(y-k)$

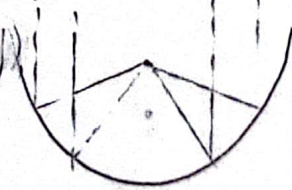
if directrix is $x = h-p$, focus is $(h+p, k)$

curve: $(y-k)^2 = 4p(x-h)$

line segment passing through the focus of a parabola and has endpoints on the parabola is called focal chord.

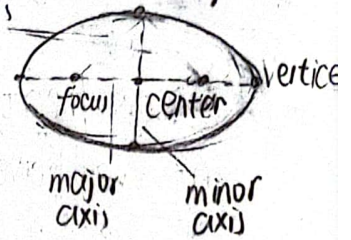
the special focal chord perpendicular to axis is latus rectum.

特殊性质: 从 focus 到 parabola 上任意一点, 该点 normal 平分 focus 与该点和 axis 方向组成的角



王: 这一块 $N(t)$ 的推导来自于, if $\vec{r}(t) \cdot \vec{r}(t) = c$, then $\vec{r}(t) \cdot \vec{r}'(t) = 0$,
即 $|\vec{r}(t)|$ 不变 $\vec{v}$ 与 $\vec{r}$ 垂直

- ellipse sum of distances from one point to each of two fixed points (focus/foci) is the same
if center is (h, k) , the lengths of major and minor axes are $2a, 2b$, where $a > b$
horizontal major axis: $\frac{(x-h)^2}{a^2} + \frac{(y-k)^2}{b^2} = 1$
vertical major axis: $\frac{(x-h)^2}{b^2} + \frac{(y-k)^2}{a^2} = 1$
the foci lie on major axis, c unit from center, where $c^2 = a^2 - b^2$

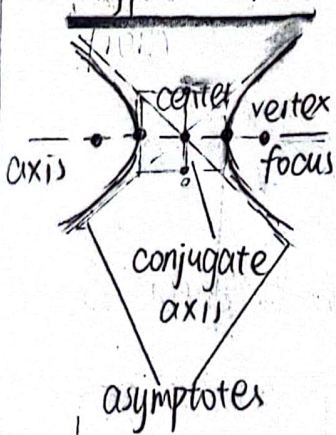


ellipse 有与 parabola 一样的特殊性质

eccentricity: $e = \frac{c}{a}$

面积用极坐标, 周长带公式

- hyperbolas: the absolute value of difference between distance from one point to each of the fixed point (focus/foci) is the same



if center is (h, k)
horizontal axis: $\frac{(x-h)^2}{a^2} - \frac{(y-k)^2}{b^2} = 1$

vertical axis: $\frac{(y-k)^2}{b^2} - \frac{(x-h)^2}{a^2} = 1$

the vertices are a units from center and foci are c units from center, where $c^2 = a^2 + b^2$

conjugate is the line segment of length $2b$ joining:

(horizontal axis) $(h, k+b)$ $(h, k-b)$

(vertical axis) $(h+b, k)$ $(h-b, k)$

hyperbolas have two asymptotes

(horizontal axis) $y = k \pm \frac{b}{a}(x-h)$

(vertical axis) $y = k \pm \frac{a}{b}(x-h)$

eccentricity: $e = \frac{c}{a}$

20. parametric equation is smooth as long as $\frac{dx}{dt}$ and $\frac{dy}{dt}$ are continuous on the demand and not simultaneously 0, except endpoints.

curve is piecewise smooth if it is smooth on each subinterval of some partition.

21. polar equation: $f(\theta)$ is a function in polar system

$\frac{dx}{d\theta} = 0, \frac{dy}{d\theta} \neq 0$: horizontal tangent

$\frac{dy}{d\theta} = 0, \frac{dx}{d\theta} \neq 0$: vertical tangent

• 两个 polar system) curves 相交时, 考虑 $(r(\theta), \theta)$ $(r(-\theta), -\theta)$ 点

22. classification of conics by eccentricity

if we have a fixed point (focus) and a fixed line (directrix).
let eccentricity (e) be the ratio of the distance between focus and the point to the distance between directrix to the point

conic

- when $0 < e < 1$: ellipse
- when $e = 1$: parabola
- when $e > 1$: hyperbola

the graph of a polar equation of the form

$$r = \frac{ed}{1 \pm e \cos \theta} \quad \text{or} \quad r = \frac{ed}{1 \pm e \sin \theta}$$

is a conic, where $e > 0$ and d is the distance between the focus at the pole and its corresponding directrix

ellipse: $b^2 = a^2 - c^2 = a^2 - (ea)^2 = a^2(1 - e^2)$

hyperbola: $b^2 = c^2 - a^2 = a^2(e^2 - 1)$

since $e = \frac{c}{a}$

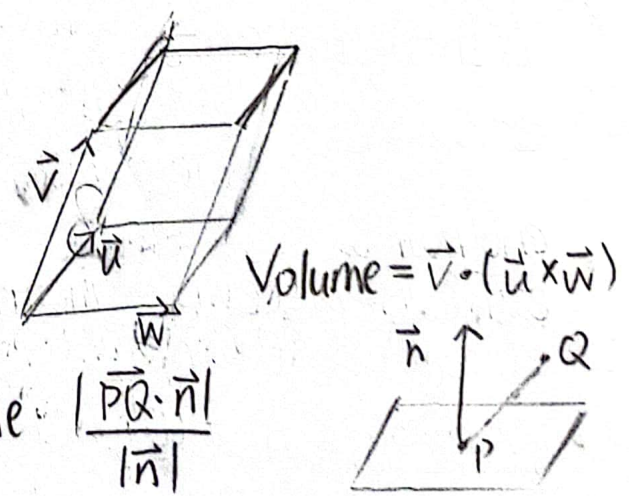
23. vector

$$\vec{v} \cdot (\vec{u} + \vec{w}) = \vec{v} \cdot \vec{u} + \vec{u} \cdot \vec{w}$$

$$\vec{v} \times (\vec{u} + \vec{w}) = \vec{v} \times \vec{u} + \vec{v} \times \vec{w}$$

$$\vec{v} \cdot (\vec{u} \times \vec{w}) = (\vec{u} \times \vec{w}) \cdot \vec{v}$$

distance from a point to the plane: $\frac{|\vec{PQ} \cdot \vec{n}|}{|\vec{n}|}$



24. 三维坐标系中图形表达

sphere: $(x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = r^2$

cylinders: 只与两个 variables 有关, 在另一方向上可无限延伸

quadric surface

即 $|\vec{r}(t)|$ 不变, $\vec{v}$ 与 $\vec{a}$ 垂直

• $\vec{a}$ 与 $\vec{T}(t)$ $\vec{N}(t)$ 关系

$$\vec{T}(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|} = \frac{\vec{v}}{|\vec{v}|} \quad \vec{N}(t) = \frac{\vec{T}'(t)}{|\vec{T}'(t)|}$$

$$\begin{aligned} \vec{a} = \vec{v}' &= [|\vec{v}| \vec{T}(t)]' = (|\vec{v}|)' \vec{T}(t) + |\vec{v}| \vec{T}'(t) \\ &= (|\vec{v}|)' \vec{T}(t) + |\vec{v}| |\vec{T}'(t)| \vec{N}(t) \\ &= a_T \vec{T}(t) + a_N \vec{N}(t) \end{aligned}$$

$$a_T = (|\vec{v}|)' = \vec{a} \cdot \vec{T}(t) = \frac{\vec{v} \cdot \vec{a}}{|\vec{v}|}$$

$$a_N = |\vec{v}| |\vec{T}'(t)| = \vec{a} \cdot \vec{N}(t) = \frac{|\vec{v} \times \vec{a}|}{|\vec{v}|} = \sqrt{|\vec{a}|^2 - a_T^2}$$

note that $a_N \geq 0$ and normal component of acceleration is called centripetal component of acceleration.

• expressing arc length using vector $S = \int_a^b |\vec{r}'(t)| dt$

arc length parameter $s(t) = \int_a^t |\vec{r}'(u)| du, a \leq t \leq b$

if s is arc length parameter and $s = f(t)$, convert $\vec{r}_t(t)$ into $\vec{r}_s(s)$

then $|\vec{r}'_s(s)| = 1$. if t is any parameter for the vector-valued function

$\vec{r}$ such that $|\vec{r}'(t)| = 1$, then t must be arc length parameter.

curvature $K = \left| \frac{d\vec{T}}{ds} \right| = |\vec{T}'(s)| \quad K = \frac{|\vec{T}'(t)|}{|\vec{r}'(t)|} = \frac{|\vec{r}'(t) \times \vec{r}''(t)|}{|\vec{r}'(t)|^3}$

[proof: $\frac{\vec{T}'(t)}{ds/dt} \approx \frac{[\vec{T}(t+\Delta t) - \vec{T}(t)]/\Delta t}{[s(t+\Delta t) - s(t)]/\Delta t} = \frac{\Delta \vec{T}}{\Delta s} = \frac{\vec{v}(t) \cdot \vec{N}(t)}{|\vec{v}(t)|}$]

if C is the graph of a twice-differentiable function given by,

then $K = \frac{|x'y'' - y'x''|}{[(x')^2 + (y')^2]^{3/2}} \approx$ [proof by calculation]

let C be a curve with curvature K at point P , the circle passing through P with radius $r = \frac{1}{K}$ is called the circle of curvature. the radius of curvature at P is r and the center is called the center of curvature

$$\begin{aligned} \vec{a} &= (|\vec{v}|)' \vec{T}(t) + |\vec{v}| |\vec{T}'(t)| \vec{N}(t) = \frac{ds}{dt} \vec{T}(t) + \frac{ds}{dt} (|\vec{v}| K) \vec{N}(t) \\ &= \frac{ds}{dt} \vec{T}(t) + K \left(\frac{ds}{dt} \right)^2 \vec{N}(t) \end{aligned}$$

• functions of several variables

if a function that can be written as a sum of functions of the form $Cx^m y^n$ (C is a real number and m and n are non-negative) is called a polynomial function of two variable.

revolution:

绕 x 轴: $y^2 + z^2 = [r(x)]^2$

绕 y 轴: $x^2 + z^2 = [r(y)]^2$

绕 z 轴: $x^2 + y^2 = [r(z)]^2$

反推时找相同的二次项系数

25. cylindrical coordinates (r, θ, z)

spherical coordinates (ρ, θ, ϕ)

ρ : radius. θ : similar to cylindrical coordinate θ

ϕ : angle between the positive z -axis to $\vec{OP}$, where P is the point

$$0 \leq \phi \leq \pi$$

转化至 rectangular coordinate

$$x = \rho \sin \phi \cos \theta \quad y = \rho \sin \phi \sin \theta \quad z = \rho \cos \phi$$

$$\rho = \sqrt{x^2 + y^2 + z^2} \quad \theta = \tan^{-1} \frac{y}{x} \quad \phi = \cos^{-1} \frac{z}{\rho}$$

转化至 cylindrical coordinates

$$r = \rho \sin \phi \quad \theta = \theta \quad z = \rho \cos \phi$$

$$\rho = \sqrt{r^2 + z^2} \quad \phi = \cos^{-1} \frac{z}{\rho}$$

26. vector-valued function ($\vec{r}(t)$ and $\vec{u}(t)$ are vector-valued function)

$$\vec{r}(t) = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k}$$

$$\vec{r}'(t) = f'(t)\vec{i} + g'(t)\vec{j} + h'(t)\vec{k}$$

$$[\vec{r}(t) \cdot \vec{u}(t)]' = \vec{r}'(t) \cdot \vec{u}(t) + \vec{r}(t) \cdot \vec{u}'(t)$$

$$[\vec{r}(t) \times \vec{u}(t)]' = \vec{r}'(t) \times \vec{u}(t) + \vec{r}(t) \times \vec{u}'(t)$$

$$[\vec{r}(w(t))]' = \vec{r}'(w(t))w'(t)$$

If $\vec{r}(t) \cdot \vec{r}(t) = c$, then $\vec{r}(t) \cdot \vec{r}'(t) = 0$ [$|\vec{r}(t)|$ 不变, 则 $\vec{a}$ 与 $\vec{v}$ 垂直]

$$\int \vec{r}(t) dt = \left[\int f(t) dt \right] \vec{i} + \left[\int g(t) dt \right] \vec{j} + \left[\int h(t) dt \right] \vec{k}$$

[注: 不定积分要加 $C = C_1\vec{i} + C_2\vec{j} + C_3\vec{k}$]

• 用 vector-valued function 解运动学

projectile motion 中: $\vec{a} = -g\vec{j}$

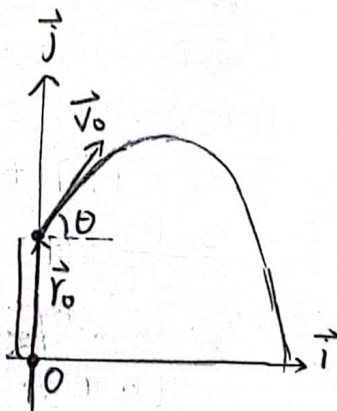
position vector 通式: $\vec{r}(t) = -\frac{1}{2}gt^2\vec{j} + t\vec{v}_0 + \vec{r}_0$

$$= (v_0 \cos \theta)t\vec{i} + \left[h + (v_0 \sin \theta)t - \frac{1}{2}gt^2 \right] \vec{j}$$

• unit tangent vector: $\vec{T}(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$

unit normal vector: $\vec{N}(t) = \frac{\vec{T}'(t)}{|\vec{T}'(t)|}$

if $\vec{T}(t) = x(t)\vec{i} + y(t)\vec{j}$, then $\vec{N}(t)$ is either $y(t)\vec{i} - x(t)\vec{j}$ or $-y(t)\vec{i} + x(t)\vec{j}$



- a rational function is the quotient of two polynomial functions
- scalar field 标量场 can be characterized by level curves/contour lines
等高线

level curves 可以被推广到三维 level surface: $f(x, y, z) = c$

- interior point: δ -neighborhood about (x_0, y_0) can be a disk centered at (x_0, y_0) with radius $\delta > 0$. every δ -neighborhood about (x_0, y_0) lies entirely in R then (x_0, y_0) is interior point

boundary point for points inside the disk, some are inside the R and some are not

open region: only contains all its interior points

closed region: contains all its interior and boundary points

- let f be a function of two variables defined, except possibly at (x_0, y_0) on an open disk centered at (x_0, y_0) , and let L be a real number, then $\lim_{(x,y) \rightarrow (x_0,y_0)} f(x,y) = L$

if for each $\epsilon > 0$, there corresponds a $\delta > 0$ such that

$$|f(x,y) - L| < \epsilon \text{ whenever } 0 < \sqrt{(x-x_0)^2 + (y-y_0)^2} < \delta$$

如果从任意方向上看结果都趋近一个值, 则极限存在, 反之则不然

continuous at point (x_0, y_0) if $\lim_{(x,y) \rightarrow (x_0,y_0)} f(x,y) = f(x_0, y_0)$

polynomial and rational functions are all continuous at their domain.

$$1) f(x,y) = f_x(x,y)$$

$$2) f(x,y) = f_y(x,y)$$

if f is a function of x and y such that f_x and f_y are continuous on the open disk R , then for every $(x,y) \in R$, $f_{xy}(x,y) = f_{yx}(x,y)$

$$1) z = f(x,y), dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy$$

$$dz = \frac{\partial z}{\partial x} \Delta x + \frac{\partial z}{\partial y} \Delta y + \epsilon_1 \Delta x + \epsilon_2 \Delta y \text{ where } \epsilon_1, \epsilon_2 \rightarrow 0 \text{ as } \Delta x, \Delta y \rightarrow 0$$

then we consider z as differentiable

if $\frac{\partial z}{\partial x}$ and $\frac{\partial z}{\partial y}$ are continuous in an open disk R

differentiable on R

if R is differentiable at (x_0, y_0) then

- chain rule: if $F(x,y,z) = 0$ then $\frac{dz}{dx} = -\frac{F_x(x,y,z)}{F_z(x,y,z)}$ where $f_y(x,y) \neq 0$

$$\text{if } F(x,y,z) = 0 \text{ then } \frac{\partial z}{\partial x} = -\frac{F_x(x,y,z)}{F_z(x,y,z)}, \frac{\partial z}{\partial y} = -\frac{F_y(x,y,z)}{F_z(x,y,z)} \text{ where } F_z(x,y,z) \neq 0$$